



本项目通过鸿蒙 App 控制 Hi3861 开发板,连接 HC-SR-04 超声波传感器,实现智能安防系统。



## 5.1 总体设计

本部分包括系统架构和系统流程。

### 5.1.1 系统架构

系统架构如图 5-1 所示,Hi3861 开发板与外设引脚连线如表 5-1 所示。

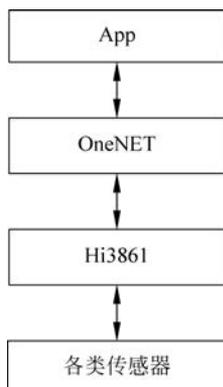


图 5-1 系统架构

表 5-1 Hi3861 开发板与外设引脚连线

Hi3861 开发板	HC-SR04 超声波	光敏传感器	蜂鸣器	OLED 串口屏
5V	VCC	VCC	VCC	VCC
GND	GND	GND	GND	GND
GPIO11	Trig	/	/	/
GPIO12	Echo	/	/	/
GPIO10	/	DO	/	/
GPIO5	/	/	I/O	/
GPIO13	/	/	/	SCL
GPIO14	/	/	/	SDA
板载 LED	/	/	/	



的高电平脉冲,脉冲的宽度、声波与返回时间有关,之后便可以计算距离,相关代码如下:

```
float GetDistance (void)
{
    static unsigned long start_time = 0, time = 0;
    float distance = 0.0;
    IoTgpioValue value = IOT_GPIO_VALUE0;
    unsigned int flag = 0;
    //超声波传感器 Trig 为 GPIO11,Echo 为 GPIO12
    IoTgpioSetDir(HI_IO_NAME_GPIO_12, IOT_GPIO_DIR_IN);
    IoTgpioSetDir(HI_IO_NAME_GPIO_11, IOT_GPIO_DIR_OUT);
    //触发 Trig
    IoTgpioSetOutputVal(HI_IO_NAME_GPIO_11, IOT_GPIO_VALUE1);
    hi_udelay(20);
    IoTgpioSetOutputVal(HI_IO_NAME_GPIO_11, IOT_GPIO_VALUE0);
    //检测 Echo 高电平时间
    while (1) {
        IoTgpioGetInputVal(HI_IO_NAME_GPIO_12, &value);
        if ( value == IOT_GPIO_VALUE1 && flag == 0) {
            start_time = hi_get_us();
            flag = 1;
        }
        if (value == IOT_GPIO_VALUE0 && flag == 1) {
            time = hi_get_us() -start_time;
            start_time = 0;
            break;
        }
    }
    //计算距离
    distance = time * 0.034 / 2;
    printf("[Distance]:%f.\r\n",distance);
    return distance;
}
```

## 5.2.2 光敏感知

通过光敏电阻感知外界光强,当外界光强低于某个阈值时,则传感器的 DO 口会给出一个高电平,根据是否接收到高电平判断板载 LED 亮灭。

```
#define LED_TEST_GPIO 9 //使用 hispark_pegasus 开发板
void GetLight (void)
{
    IoTgpioValue value = IOT_GPIO_VALUE0;
    //初始化 LED 的 GPIO
    IoTgpioInit(LED_TEST_GPIO);
    //设置为输入/输出
    IoTgpioSetDir(LED_TEST_GPIO, IOT_GPIO_DIR_OUT);
    //设置光敏传感器的 DO 口
    IoTgpioSetDir(HI_IO_NAME_GPIO_10, IOT_GPIO_DIR_IN);
    if(led_flag==2){
        IoTgpioSetDir(LED_TEST_GPIO, 1); //LED 亮
    }
    else{
        IoTgpioGetInputVal(HI_IO_NAME_GPIO_10, &value);
        if ( value == IOT_GPIO_VALUE1 ) {
```

```

        IoTGPIOSetDir(LED_TEST_GPIO, 1); //LED 亮
        led_flag = 1;
        printf("on\n");
    }
    if (value == IOT_GPIO_VALUE0) {
        IoTGPIOSetDir(LED_TEST_GPIO, 0); //LED 灭
        led_flag = 0;
        printf("off\n");
    }
}
}

```

### 5.2.3 蜂鸣器控制

通过简单的高低电平控制声响。

```

void BeepRing(void)
{
    //初始化 GPIO
    IoTGPIOInit(HI_IO_NAME_GPIO_5);
    //设置为输出
    IoTGPIOSetDir(HI_IO_NAME_GPIO_5, IOT_GPIO_DIR_OUT);
    //GPIO 复用
    hi_io_set_func(HI_IO_NAME_GPIO_5, HI_IO_FUNC_GPIO_5_GPIO);
    //输出低电平
    IoTGPIOSetOutputVal(HI_IO_NAME_GPIO_5, 0);
    beep_flag=0;
    printf("BeepRing\n");
}

void BeepStop(void)
{
    //初始化 GPIO
    IoTGPIOInit(HI_IO_NAME_GPIO_5);
    //设置为输出
    IoTGPIOSetDir(HI_IO_NAME_GPIO_5, IOT_GPIO_DIR_OUT);
    //GPIO 复用
    hi_io_set_func(HI_IO_NAME_GPIO_5, HI_IO_FUNC_GPIO_5_GPIO);
    //输出高电平
    IoTGPIOSetOutputVal(HI_IO_NAME_GPIO_5, 1);
    beep_flag=1;
    printf("BeepStop\n");
}

```

### 5.2.4 OLED 显示

SSD1306 逻辑功能代码如下：

```

void OLED(void)
{
    IoTGPIOInit(HI_IO_NAME_GPIO_13);
    IoTGPIOInit(HI_IO_NAME_GPIO_14);
    hi_io_set_func(HI_IO_NAME_GPIO_13, HI_IO_FUNC_GPIO_13_I2C0_SDA);
    hi_io_set_func(HI_IO_NAME_GPIO_14, HI_IO_FUNC_GPIO_14_I2C0_SCL);
    IoTI2cInit(0, OLED_I2C_BAUDRATE);
    usleep(20*1000);
}

```

```

    ssd1306_Init();
    ssd1306_Fill(Black);
    ssd1306_SetCursor(0, 0);
    if(distance_flag==0){
        ssd1306_DrawString("Be Carefully!", Font_11x18, White);
        ssd1306_UpdateScreen();
        printf("test1");
    }
    else{
        ssd1306_DrawString("Safe", Font_11x18, White);
        ssd1306_UpdateScreen();
        printf("test2");
    }
}
}

```

### 5.2.5 WiFi 模块

WiFi 连接相关代码如下：

```

void wifi_wpa_event_cb(const hi_wifi_event *hisi_event)
{
    if (hisi_event == NULL)
        return;
    switch (hisi_event->event) {
        case HI_WIFI_EVT_SCAN_DONE:
            printf("WiFi: Scan results available\n");
            break;
        case HI_WIFI_EVT_CONNECTED:
            printf("WiFi: Connected\n");
            netifapi_dhcp_start(g_lwip_netif);
            wifi_ok_flg = 1;
            break;
        case HI_WIFI_EVT_DISCONNECTED:
            printf("WiFi: Disconnected\n");
            netifapi_dhcp_stop(g_lwip_netif);
            hi_sta_reset_addr(g_lwip_netif);
            break;
        case HI_WIFI_EVT_WPS_TIMEOUT:
            printf("WiFi: wps is timeout\n");
            break;
        default:
            break;
    }
}

int hi_wifi_start_connect(void)
{
    int ret;
    errno_t rc;
    hi_wifi_assoc_request assoc_req = {0};
    rc = memcpy_s(assoc_req.ssid, HI_WIFI_MAX_SSID_LEN + 1, "OCF24", 8);
    if (rc != EOK) {
        return -1;
    }
    //热点加密方式

```

```

    assoc_req.auth = HI_WIFI_SECURITY_WPA2PSK;
    //热点密码
    memcpy(assoc_req.key, "xxxxxxxx", 8);
    ret = hi_wifi_sta_connect(&assoc_req);
    if (ret != HISI_OK) {
        return -1;
    }
    return 0;
}
int hi_wifi_start_sta(void)
{
    int ret;
    char ifname[WIFI_IFNAME_MAX_SIZE + 1] = {0};
    int len = sizeof(ifname);
    const unsigned char wifi_vap_res_num = APP_INIT_VAP_NUM;
    const unsigned char wifi_user_res_num = APP_INIT_USR_NUM;
    unsigned int num = WIFI_SCAN_AP_LIMIT;
    ret = hi_wifi_sta_start(ifname, &len);
    if (ret != HISI_OK) {
        return -1;
    }
    ret = hi_wifi_register_event_callback(wifi_wpa_event_cb);
    if (ret != HISI_OK) {
        printf("register wifi event callback failed\n");
    }
    g_lwip_netif = netifapi_netif_find(ifname);
    if (g_lwip_netif == NULL) {
        printf("%s: get netif failed\n", __FUNCTION__);
        return -1;
    }
    //开始扫描附近的WiFi热点
    ret = hi_wifi_sta_scan();
    if (ret != HISI_OK) {
        return -1;
    }
    sleep(5);
    hi_wifi_ap_info *pst_results = malloc(sizeof(hi_wifi_ap_info) * WIFI_SCAN_AP_
LIMIT);
    if (pst_results == NULL) {
        return -1;
    }
    //将扫描到的热点结果进行存储
    ret = hi_wifi_sta_scan_results(pst_results, &num);
    if (ret != HISI_OK) {
        free(pst_results);
        return -1;
    }
    //打印扫描到的所有热点
    for (unsigned int loop = 0; (loop < num) && (loop < WIFI_SCAN_AP_LIMIT); loop++) {
        printf("SSID: %s\n", pst_results[loop].ssid);
    }
    free(pst_results);
    //开始接入热点
    ret = hi_wifi_start_connect();
    if (ret != 0) {

```

```

        return -1;
    }
    return 0;
}
void wifi_sta_task(void *arg)
{
    arg = arg;
    //连接热点
    hi_wifi_start_sta();
    while(wifi_ok_flg == 0)
    {
        usleep(30000);
    }
}
usleep(2000000);

```

## 5.2.6 OneNET 云平台

本部分包括创建账号、创建产品、添加设备和相关代码。

### 1. 创建账号

登录网页 <https://open.iot.10086.cn/passport/reg/>，按要求填写注册信息后进行实名认证。

### 2. 创建产品

进入 Studio 平台后，在全部产品服务中选择多协议接入。单击“添加产品”按钮，在弹出页面中按照提示填写产品信息。本项目采用 MQTT 协议接入，如图 5-3 所示。

图 5-3 创建产品

### 3. 添加设备

单击“设备管理”，选择“添加设备”，按照提示填写相关信息，如图 5-4 所示。



图 5-4 添加设备

### 4. 相关代码

下面给出实现连接 OneNET 云平台及整个系统的逻辑控制代码。

```
void onenet_cmd_rsp_cb(uint8_t *recv_data, size_t recv_size, uint8_t **resp_data,
size_t *resp_size)
{
    printf("recv data is %.*s\n", recv_size, recv_data);
    strcpy(temp1, (char *) (recv_data)); //暂存 recv data
    int messageCode = (temp1[2] - '0');
    printf("messageCode is %d\n", messageCode);
    if(messageCode==0) {
        BeepStop();
        printf("Beep\n");
    }
    if(messageCode==1) {
        IoTGpioSetDir(LED_TEST_GPIO, 1); //LED 亮
        led_flag = 2;
        printf("LED ON\n");
    }
    if(messageCode==2) {
        IoTGpioSetDir(LED_TEST_GPIO, 1); //LED 灭
        led_flag = 0;
        printf("LED OFF\n");
    }
    *resp_data = NULL;
    *resp_size = 0;
}
int onenet_test(void)
{
    device_info_init(ONENET_INFO_DEVID, ONENET_INFO_PROID, ONENET_INFO_AUTH,
ONENET_INFO_APIKEY, ONENET_MASTER_APIKEY);
    onenet_mqtt_init();
}
```

```

onenet_set_cmd_rsp_cb(onenet_cmd_rsp_cb);
IoTWatchDogDisable();
while (1)
{
    GetLight();
    temp = GetDistance();
    OLED();
    //连续判断,防止错判
    if(temp<3){
        count++;
    }
    else{
        count=0;
    }
    if(temp<3&&count>3){
        BeepRing(); //蜂鸣器响
        printf("[Beep]:%d.\r\n",beep_flag);
        distance_flag=0;
        printf("[person]:%d.\r\n",distance_flag);
    }
    else{
        BeepStop(); //蜂鸣器不响
        printf("[person]:%d.\r\n",distance_flag);
        distance_flag=1;
    }
    //上传至 OneNET
    if (onenet_mqtt_upload_digit("person", distance_flag) < 0)
    {
        printf("upload has an error, stop uploading");
        //break;
    }
    else
    {
        printf("buffer : {\\"person\\":%d} \r\n", distance_flag);
    }
    sleep(1);
}
return 0;
}

```

## 5.2.7 前端模块

本部分包括界面设计和发送 POST 请求。

### 1. 界面设计

```

<?xml version="1.0" encoding="utf-8"?>
<DirectionalLayout
    xmlns:ohos="http://schemas.huawei.com/res/ohos"
    ohos:height="match_parent"
    ohos:width="match_parent"
    ohos:alignment="horizontal_center"
    ohos:orientation="vertical">
<Text
    ohos:id="\$+id:text_type_get"
    ohos:height="60vp"

```

```

        ohos:width="match_parent"
        ohos:text_alignment="center"
        ohos:layout_alignment="horizontal_center"
        ohos:text="GET 请求"
        ohos:text_size="30vp"
    />
<Text
    ohos:id="$+id:text_type_post"
    ohos:height="60vp"
    ohos:text_alignment="center"
    ohos:width="match_parent"
    ohos:background_element="#ed6262"
    ohos:layout_alignment="horizontal_center"
    ohos:text="POST 请求"
    ohos:text_size="30vp"
/>
<ScrollView
    ohos:height="match_parent"
    ohos:width="match_parent"
    >
    <DirectionalLayout
        ohos:height="match_parent"
        ohos:width="match_parent">
        <Text
            ohos:id="$+id:text_result"
            ohos:height="match_parent"
            ohos:multiple_lines="true"
            ohos:text_alignment="center"
            ohos:width="match_parent"
            ohos:layout_alignment="horizontal_center"
            ohos:text="显示结果"
            ohos:text_size="20vp"
        />
    </DirectionalLayout>
</ScrollView>
</DirectionalLayout>

```

## 2. 发送 POST 请求

```

package com.example.afinal.slice;
import com.example.afinal.ResourceTable;
import ohos.aafwk.ability.AbilitySlice;
import ohos.aafwk.content.Intent;
import ohos.agp.components.Component;
import ohos.agp.components.Text;
import okhttp3.*;
import java.io.IOException;
public class MainAbilitySlice extends AbilitySlice {
    //private static AbilityForm textResult;
    Text TextGet, TextPost, textResult;
    private boolean status;
    final String cloud_url =
        "http://api.heclouds.com/cmds?device_id=962845387";
    @Override
    public void onStart(Intent intent) {
        super.onStart(intent);
    }
}

```

```

super.setUIContent(ResourceTable.Layout_ability_main);
TextGet = findComponentById(ResourceTable.Id_text_type_get);
TextPost = findComponentById(ResourceTable.Id_text_type_post);
textResult = findComponentById(ResourceTable.Id_text_result);
TextGet.setClickListener(new Component.ClickedListener() {
    @Override
    public void onClick(Component component) {
        OkHttpClient client = new OkHttpClient();
        Request.Builder requestBuilder = new Request.Builder();
        requestBuilder.addHeader("api-key", "CT0J7NvniU4E5hsdH4emD =
FzKs0=");

        HttpUrl.Builder urlBuilder = HttpUrl.parse("http://api.heclouds.
com/devices/962845387/datapoints").newBuilder(); //todo 接口链接
        urlBuilder.addQueryParameter("datastream_id", "temperature");
        //参数
        urlBuilder.addQueryParameter("limit", "4"); //密钥
        requestBuilder.url(urlBuilder.build());
        Call call = client.newCall(requestBuilder.build());
        call.enqueue(new Callback() {
            @Override
            public void onFailure(Call call, IOException e) {
                //todo 失败回调需要回到主线程显示结果
                getUITaskDispatcher().asyncDispatch(new Runnable()
{
                    @Override
                    public void run() {
                        textResult.setText(e.getMessage());
                    }
                });
            }
            @Override
            public void onResponse(Call call, Response response) throws
IOException {
                if (response.isSuccessful()) {
                    String result = response.body().string();
                    //处理界面需要切换到界面线程处理
                    getUITaskDispatcher().asyncDispatch(new Runnable() {
                        @Override
                        public void run() {
                            textResult.setText(result);
                        }
                    });
                }
            }
        });
    }
});
TextPost.setClickListener(new Component.ClickedListener() {
    @Override
    public void onClick(Component component) {
        textResult.setText("post can be pressed");
        OkHttpClient client = new OkHttpClient();
        FormBody body = new FormBody.Builder()
            .add("temperature", "77")//日期参数
            .build();
    }
});

```

```

Request request = new Request.Builder()
    .header("api-key", "CT0J7NvniU4E5hsdH4emD=FzKs0=")
    .url("http://api.heclouds.com/cmds?device_id=962845387")
    .post(body)
    .build();
Call call = client.newCall(request);
call.enqueue(new Callback() {
    @Override
    public void onFailure(Call call, IOException e) {
        //失败回调需要回到主线程显示结果
        getUITaskDispatcher().asyncDispatch(new Runnable()
        {
            @Override
            public void run() {
                textResult.setText(e.getMessage());
            }
        });
    }
    @Override
    public void onResponse(Call call, Response response) throws
IOException {
        if (response.isSuccessful()) {
            String result = response.body().string();
            //处理界面需要切换到界面线程处理
            //失败回调需要回到主线程显示结果
            getUITaskDispatcher().asyncDispatch(new Runnable() {
                @Override
                public void run() {
                    textResult.setText(result);
                }
            });
        }
    }
});
}
});
}
}

```

### 5.3 产品展示

Hi3861 开发板的实现效果如图 5-5 所示,串口监视器效果如图 5-6 所示,鸿蒙 App 的实现效果如图 5-7 所示。



图 5-5 Hi3861 开发板实现效果

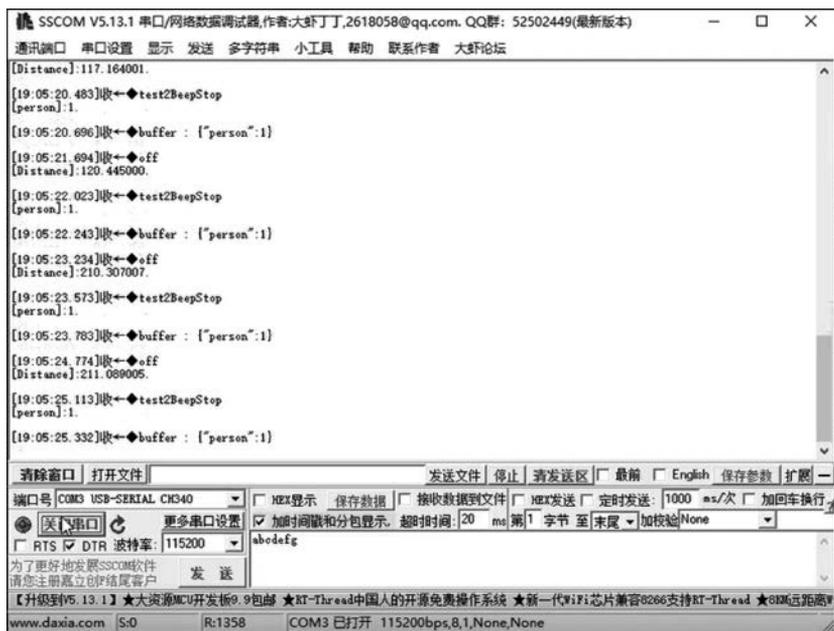


图 5-6 串口监视器效果

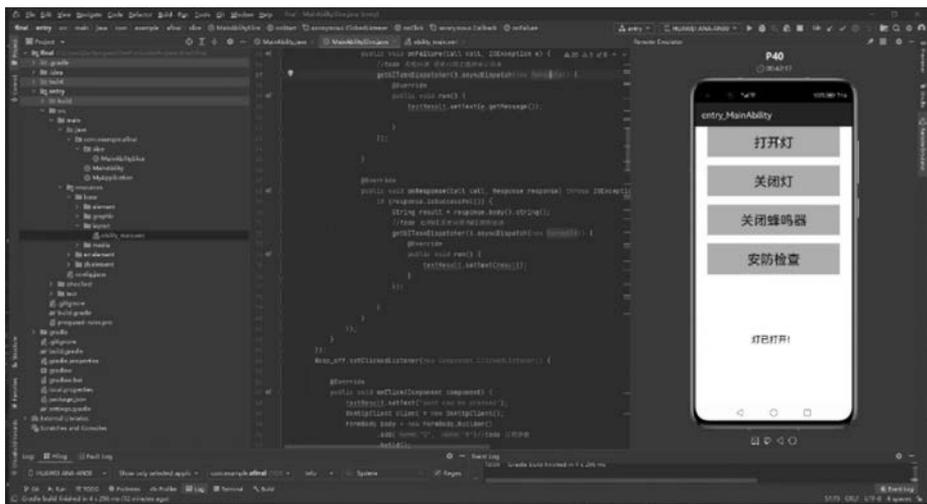


图 5-7 App 页面效果

## 5.4 元件清单

完成本项目所需的元件及数量如表 5-2 所示。

表 5-2 元件清单

元件/测试仪表	数 量	元件/测试仪表	数 量
面包板	1 个	光敏模块	1 个
Hi3861	1 个	蜂鸣器	1 个
HC-SR04 超声波传感器	1 个	OLED 串口屏	1 个